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Mechatronics, IEEE/ASME Transactions on
 Volume 8, Issue 2, June 2003 Page(s):178 - 187
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3. **On the modeling and control of an experimental harvester machine manipulator**
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Intelligent Robots and Systems, 1997. IROS '97.. Proceedings of the 1997 IEEE/RSJ International Conference on
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... servo-control applications in a **simulation** or a ... where is the line-oscillation **frequency** observed (about 3 Hz ... into the damping of the **gear train** connected to its ...
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B Mu - 1996 - collectionscanada.ca

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... housing angular position (rad) y g **gear-train** angular position ... no artificial imbalance, the magnitude ofthe **oscillations** at the ... **Frequency**, periods/engine cycle ...
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T Bernardi, B Lewis, M Rosmarin - cats.rpi.edu

... of the motors, backlash in the **gear train**, and the ... loop rates, and time delays in the **simulation**. ... By finding the **frequency** of **oscillation** and measuring the ...
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K Menon, K Krishnamurthy - Mechatronics, 1999 - Elsevier
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